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Strong convergence of a modified iterative algorithm for hierarchical fixed point problems and variational inequalities

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wangyuanheng@yahoo.com.cn¹Department of Mathematics,
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Zhejiang, 321004, China**Abstract**

This article aims to deal with a new modified iterative projection method for solving a hierarchical fixed point problem. It is shown that under certain approximate assumptions of the operators and parameters, the modified iterative sequence $\{x_n\}$ converges strongly to a fixed point x^* of T , also the solution of a variational inequality. As a special case, this projection method solves some quadratic minimization problem. The results here improve and extend some recent corresponding results by other authors.

MSC: 47H10; 47J20; 47H09; 47H05**Keywords:** hierarchical fixed point; nonexpansive mapping; Lipschitzian and strongly monotone mapping; quadratic minimization; modified iterative projection algorithm

1 Introduction

Let Ω be a nonempty closed convex subset of a real Hilbert space H with the inner product $\langle \cdot, \cdot \rangle$ and the norm $\| \cdot \|$. Recall that a mapping $T : \Omega \rightarrow H$ is called L -Lipschitzian if there exists a constant L such that $\|Tx - Ty\| \leq L\|x - y\|$, $\forall x, y \in \Omega$. In particular, if $L \in [0, 1)$, then T is said to be a contraction; if $L = 1$, then T is called a nonexpansive mapping. We denote by $\text{Fix}(T)$ the set of the fixed points of T , i.e., $\text{Fix}(T) = \{x \in \Omega : Tx = x\}$.

A mapping $F : \Omega \rightarrow H$ is called η -strongly monotone if there exists a constant $\eta \geq 0$ such that

$$\langle x - y, Fx - Fy \rangle \geq \eta \|x - y\|^2, \quad \forall x, y \in \Omega.$$

In particular, if $\eta = 0$, then F is said to be monotone.

A mapping $P_\Omega : H \rightarrow \Omega$ is called a metric projection if there exists a unique nearest point in Ω denoted by $P_\Omega x$ such that

$$\|x - P_\Omega x\| = \inf_{y \in \Omega} \|x - y\|, \quad \forall x \in H.$$

Recently many authors investigated the fixed point problem of nonexpansive mappings, generalized nonexpansive mappings with C -conditions, a family of finite or infinite nonexpansive mappings and pseudo-contractions and obtained many useful results; see, for example, [1–12] and the references therein.

Now, we focus on the following problem.

To find a hierarchical fixed point of T with respect to another operator S is to find an $x^* \in \text{Fix}(T)$ satisfying

$$\langle x^* - Sx^*, x^* - x \rangle \leq 0, \quad \forall x \in \text{Fix}(T), \quad (1)$$

which is equivalent to the following fixed point problem: to find an $x^* \in \Omega$ that satisfies $x^* = P_{\text{Fix}(T)} Sx^*$. We know that $\text{Fix}(T)$ is closed and convex, so the metric projection $P_{\text{Fix}(T)}$ is well defined.

It is well known that the iterative methods for finding hierarchical fixed points of non-expansive mappings can also be used to solve a convex minimization problem; see, for example, [13, 14] and the references therein. In 2006, Marino and Xu [15] considered the following general iterative method:

$$x_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n A) T x_n, \quad n \geq 0, \quad (2)$$

where f is a contraction, T is a nonexpansive mapping, A is a bounded linear strongly positive operator: $\langle Ax, x \rangle \geq \zeta \|x\|^2$, $\forall x \in H$, for some $\zeta > 0$. And it is proved that if the sequence $\{\alpha_n\}$ of parameters satisfies appropriate conditions, then the sequence $\{x_n\}$ generated by (2) converges strongly to the unique solution of the variational inequality

$$\langle (\gamma f - A)x^*, x - x^* \rangle \leq 0, \quad \forall x \in C \in H,$$

which is the optimality condition for the minimization problem

$$\min_{x \in C} \left\{ \frac{1}{2} \langle Ax, x \rangle - h(x) \right\},$$

where h is a potential function for γf , i.e., $h'(x) = \gamma f(x)$, $\forall x \in H$.

In 2010, Tian [16] introduced the general steepest-descent method

$$x_{n+1} = \alpha_n \rho f(x_n) + (I - \alpha_n \mu F) T x_n, \quad \forall n \geq 0, \quad (3)$$

where F is an L -Lipschitzian and η -strongly monotone operator. Under certain approximate conditions, the sequence $\{x_n\}$ generated by (3) converges strongly to a fixed point of T , which solves the variational inequality

$$\langle (\rho f - \mu F)x^*, x - x^* \rangle \leq 0, \quad \forall x \in \text{Fix}(T).$$

Very recently, Ceng *et al.* [17] investigated the following iterative method:

$$x_{n+1} = P_{\Omega} [\alpha_n \rho U x_n + (I - \alpha_n \mu F) T x_n], \quad \forall n \geq 0, \quad (4)$$

where U is a Lipschitzian (possibly non-self) mapping, and F is a Lipschitzian and strongly monotone mapping. They proved that under some approximate assumptions on the operators and parameters, the sequence $\{x_n\}$ generated by (4) converges strongly to the unique

solution of the variational inequality

$$\langle (\rho U - \mu F)x^*, x - x^* \rangle \leq 0, \quad \forall x \in \text{Fix}(T). \quad (5)$$

On the other hand, in 2010, Yao *et al.* [18] investigated an iterative method for a hierarchical fixed point problem by

$$\begin{cases} y_n = \beta_n Sx_n + (1 - \beta_n)x_n, \\ x_{n+1} = P_\Omega[\alpha_n f(x_n) + (1 - \alpha_n)Ty_n], \end{cases} \quad \forall n \geq 0, \quad (6)$$

where $S : \Omega \rightarrow \Omega$ is a nonexpansive mapping. Under some approximate assumptions of the parameters, the sequence $\{x_n\}$ generated by (6) converges strongly to the unique solution of the variational inequality

$$x^* \in F(T), \quad \langle (I - f)x^*, x - x^* \rangle \geq 0, \quad \forall x \in \text{Fix}(T).$$

Motivated and inspired by the above research work, we introduce the following modified iterative method for a hierarchical fixed point problem:

$$\begin{cases} y_n = \beta_n Sx_n + (1 - \beta_n)x_n, \\ x_{n+1} = P_\Omega[\alpha_n \rho U(x_n) + (I - \alpha_n \mu F)Ty_n], \end{cases} \quad \forall n \geq 0, \quad (7)$$

where S, T are nonexpansive mappings with $\text{Fix}(T) \neq \emptyset$, U is a γ -Lipschitzian (possibly non-self) mapping, F is an L -Lipschitzian and η -strongly monotone operator. We prove that the sequence $\{x_n\}$ generated by (7) converges strongly to the unique solution of the variational inequality (5) if the operators and parameters satisfy some approximate conditions. As a special case, this projection method also solves the quadratic minimization problem $x_n \rightarrow \arg\min_{x \in \text{Fix}(T)} \|x\|^2$.

Obviously, (2), (3), (4) and (6) are some special cases of (7), respectively. So, our results improve and extend many recent corresponding results of other authors such as [5, 13, 15–19].

2 Preliminaries

This section contains some lemmas which will be used in the proofs of our main results in the following section.

Lemma 2.1 [18] *Let $x \in H$ and $z \in \Omega$ be any points. The following results hold.*

(1) $P_\Omega : H \rightarrow \Omega$ is nonexpansive and $z = P_\Omega x$ if and only if the following relation holds:

$$\langle x - z, y - z \rangle \leq 0, \quad \forall y \in \Omega;$$

(2) $z = P_\Omega x$ if and only if the following relation holds:

$$\|x - z\|^2 \leq \|x - y\|^2 - \|y - z\|^2, \quad \forall y \in \Omega.$$

Lemma 2.2 [4] *Let H be a real Hilbert space, $\forall x, y \in H$, the following inequality holds:*

$$\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle.$$

Lemma 2.3 [17] *Let $U : \Omega \mapsto H$ be a γ -Lipschitzian mapping with a constant $\gamma \geq 0$ and let $F : \Omega \mapsto H$ be a k -Lipschitzian and η -strongly monotone mapping with constants $k, \eta > 0$, then for $0 \leq \rho\gamma < \mu\eta$,*

$$\langle x - y, (\mu F - \rho U)x - (\mu F - \rho U)y \rangle \geq (\mu\eta - \rho\gamma)\|x - y\|^2, \quad \forall x, y \in \Omega.$$

That is to say, the operator $\mu F - \rho U$ is $\mu\eta - \rho\gamma$ -strongly monotone.

Lemma 2.4 [10] (Demiclosedness principle) *Let Ω be a nonempty closed convex subset of a real Hilbert space H and let $T : \Omega \mapsto \Omega$ be a nonexpansive mapping with $\text{Fix}(T) \neq \emptyset$. If $\{x_n\}$ is a sequence in Ω weakly converging to x and $\{(I - T)x_n\}$ converges strongly to y , then $(I - T)x = y$. In particular, if $y = 0$, then $x \in F(T)$.*

Lemma 2.5 [19] *Suppose that $\lambda \in (0, 1)$ and $\mu > 0$. Let $F : \Omega \mapsto H$ be an L -Lipschitzian and η -strongly monotone operator with constants $L, \eta > 0$. In association with a nonexpansive mapping $T : \Omega \mapsto \Omega$, define the mapping $T^\lambda : \Omega \mapsto H$ by*

$$T^\lambda x := Tx - \lambda\mu FT(x), \quad \forall x \in \Omega.$$

Then T^λ is a contraction provided $\mu < \frac{2\eta}{L^2}$, that is,

$$\|T^\lambda x - T^\lambda y\| \leq (1 - \lambda v)\|x - y\|, \quad \forall x, y \in \Omega,$$

where $v = 1 - \sqrt{1 - \mu(2\eta - \mu L^2)}$.

Lemma 2.6 [20] *Let $\{\alpha_n\}$ be a sequence of nonnegative real numbers satisfying the following relation:*

$$\alpha_{n+1} \leq (1 - \gamma_n)\alpha_n + \delta_n,$$

with conditions

- (1) $\{\gamma_n\} \subset (0, 1)$, $\sum_{n=1}^{\infty} \gamma_n = \infty$;
- (2) $\limsup_{n \rightarrow \infty} \frac{\delta_n}{\gamma_n} = 0$ or $\sum_{n=1}^{\infty} |\delta_n| < \infty$.

Then $\lim_{n \rightarrow \infty} \alpha_n = 0$.

3 Main results

Theorem 3.1 *Let Ω be a nonempty closed convex subset of a real Hilbert space H and let $x_0 \in \Omega$ be any given initial guess. Let $S, T : \Omega \mapsto \Omega$ be nonexpansive mappings such that $\text{Fix}(T) \neq \emptyset$. Let $F : \Omega \mapsto H$ be an L -Lipschitzian and η -strongly monotone (possibly non-self) operator with coefficients $L, \eta > 0$. Let $U : \Omega \mapsto H$ be a γ -Lipschitzian (possibly non-self) mapping with a coefficient $\gamma \geq 0$. Suppose the parameters satisfy $0 < \mu < \frac{2\eta}{L^2}$, $0 \leq \rho\gamma < v$, where $v = 1 - \sqrt{1 - \mu(2\eta - \mu L^2)}$. And suppose the sequences $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy the following conditions:*

- (i) $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\sum_{n=0}^{\infty} \alpha_n = \infty$;
- (ii) $\lim_{n \rightarrow \infty} \frac{\beta_n}{\alpha_n} = 0$;
- (iii) $\sum_{n=0}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$ and $\sum_{n=0}^{\infty} |\beta_{n+1} - \beta_n| < \infty$.

Then the sequence $\{x_n\}$ generated by (7) converges strongly to a fixed point x^* of T , which is the unique solution of the variational inequality (5). In particular, if we take $U = 0$, $F = I$, then x_n defined by (7) converges in norm to the minimum norm fixed point x^* of T , namely, the point x^* is the unique solution to the quadratic minimization problem $x^* = \operatorname{argmin}_{x \in \operatorname{Fix}(T)} \|x\|^2$.

Proof We divide the proof into six steps.

Step 1. We first show that the variational inequality (5) has only one solution. Observe that the constants satisfy $0 \leq \rho\gamma < v$ and

$$\begin{aligned} L \geq \eta &\iff L^2 \geq \eta^2 \\ &\iff 1 - 2\mu\eta + \mu^2 L^2 \geq 1 - 2\mu\eta + \mu^2 \eta^2 \\ &\iff \sqrt{1 - \mu(2\eta - \mu L^2)} \geq 1 - \mu\eta \\ &\iff \mu\eta \geq 1 - \sqrt{1 - \mu(2\eta - \mu L^2)} \\ &\iff \mu\eta \geq v, \end{aligned}$$

therefore the operator $\mu F - \rho U$ is $\mu\eta - \rho\gamma$ -strongly monotone, and we get the uniqueness of the solution of the variational inequality (5) and denote it by $x^* \in \operatorname{Fix}(T)$.

Step 2. Then we get that the sequences $\{x_n\}$ and $\{y_n\}$ are bounded. By condition (ii), without loss of generality, we may assume $\beta_n \leq \alpha_n, \forall n \geq 0$. Taking a fixed point $p \in \operatorname{Fix}(T)$, we have

$$\begin{aligned} \|y_n - p\| &= \|\beta_n Sx_n + (1 - \beta_n)x_n - p\| \\ &\leq \beta_n \|Sx_n - Sp\| + \beta_n \|Sp - p\| + (1 - \beta_n)\|x_n - p\| \\ &\leq \|x_n - p\| + \beta_n \|Sp - p\|. \end{aligned} \quad (8)$$

On the other hand, denoting $V_n = \alpha_n \rho U x_n + (I - \alpha_n \mu F) T y_n$, from (7) we get

$$\begin{aligned} \|x_{n+1} - p\| &= \|P_{\Omega}(V_n) - P_{\Omega}p\| \\ &\leq \|\alpha_n \rho U x_n + (I - \alpha_n \mu F) T y_n - p\| \\ &\leq \alpha_n \|\rho U x_n - \mu F p\| + \|(I - \alpha_n \mu F) T y_n - (I - \alpha_n \mu F) T p\| \\ &\leq \alpha_n \rho\gamma \|x_n - p\| + \alpha_n \|(\rho U - \mu F)p\| + (1 - \alpha_n v)\|y_n - p\|. \end{aligned} \quad (9)$$

Together with (8) and (9), we have

$$\begin{aligned} \|x_{n+1} - p\| &\leq \alpha_n \rho\gamma \|x_n - p\| + (1 - \alpha_n v)\|x_n - p\| \\ &\quad + \alpha_n \|(\rho U - \mu F)p\| + (1 - \alpha_n v)\beta_n \|Sp - p\| \\ &\leq [1 - \alpha_n(v - \rho\gamma)]\|x_n - p\| + \alpha_n [\|(\rho U - \mu F)p\| + \|Sp - p\|] \end{aligned}$$

$$= [1 - \alpha_n(v - \rho\gamma)]\|x_n - p\| \\ + \alpha_n(v - \rho\gamma) \left[\frac{1}{v - \rho\gamma} (\|(\rho U - \mu F)p\| + \|Sp - p\|) \right].$$

Hence

$$\|x_n - p\| \leq \max \left\{ \|x_0 - p\|, \frac{1}{v - \rho\gamma} (\|(\rho U - \mu F)p\| + \|Sp - p\|) \right\}.$$

We get the sequence $\{x_n\}$ is bounded, and so are $\{y_n\}$, $\{Sx_n\}$, $\{Tx_n\}$, $\{FTy_n\}$, $\{Ux_n\}$.

Step 3. Next we show that $\|x_{n+1} - x_n\| \rightarrow 0$ as $n \rightarrow \infty$. Estimate $\|y_n - y_{n-1}\|$

$$\begin{aligned} \|y_n - y_{n-1}\| &= \|\beta_n Sx_n - (1 - \beta_n)x_n - (\beta_{n-1} Sx_{n-1} - (1 - \beta_{n-1})x_{n-1})\| \\ &\leq \beta_n \|Sx_n - Sx_{n-1}\| + (1 - \beta_n) \|x_n - x_{n-1}\| \\ &\quad + |\beta_n - \beta_{n-1}| (\|Sx_{n-1}\| + \|x_{n-1}\|) \\ &\leq \|x_n - x_{n-1}\| + |\beta_n - \beta_{n-1}| M, \end{aligned} \quad (10)$$

where M is a constant such that

$$\begin{aligned} \sup_{n \geq 1} \{ \|Sx_n\| + \|x_n\| + \rho \|Ux_n\| + \|\mu FTy_n\| + \|Sx^* - x^*\| \cdot \|x_{n+1} - x^*\| \} &\leq M, \\ \|x_{n+1} - x_n\| &= \|P_\Omega(V_n) - P_\Omega(V_{n-1})\| \\ &\leq \|\alpha_n \rho (Ux_n - Ux_{n-1}) + (\alpha_n - \alpha_{n-1}) \rho Ux_{n-1} + (I - \alpha_n \mu F)Ty_n \\ &\quad - (I - \alpha_n \mu F)Ty_{n-1} + (I - \alpha_n \mu F)Ty_{n-1} - (I - \alpha_{n-1} \mu F)Ty_{n-1}\| \\ &\leq \alpha_n \rho \gamma \|x_n - x_{n-1}\| + (1 - \alpha_n v) \|y_n - y_{n-1}\| \\ &\quad + |\alpha_n - \alpha_{n-1}| (\|\rho Ux_{n-1}\| + \|\mu FTy_{n-1}\|). \end{aligned} \quad (11)$$

Substituting (10) into (11), we obtain

$$\begin{aligned} \|x_{n+1} - x_n\| &\leq \alpha_n \rho \gamma \|x_n - x_{n-1}\| + (1 - \alpha_n v) \|x_n - x_{n-1}\| + (1 - \alpha_n v) |\beta_n - \beta_{n-1}| M \\ &\quad + |\alpha_n - \alpha_{n-1}| (\|\rho Ux_{n-1}\| + \|\mu FTy_{n-1}\|) \\ &\leq [1 - \alpha_n(v - \rho\gamma)] \|x_n - x_{n-1}\| + (|\alpha_n - \alpha_{n-1}| + |\beta_n - \beta_{n-1}|) M. \end{aligned}$$

Notice the conditions (i) and (iii), by Lemma 2.6, we have $\|x_{n+1} - x_n\| \rightarrow 0$ as $n \rightarrow \infty$.

Step 4. Next we show that $\|x_n - Tx_n\| \rightarrow 0$ as $n \rightarrow \infty$.

$$\begin{aligned} \|x_n - Tx_n\| &\leq \|x_n - x_{n+1}\| + \|x_{n+1} - Tx_n\| \\ &\leq \|x_n - x_{n+1}\| + \|\text{Proj}_\Omega(V_n) - \text{Proj}_\Omega Tx_n\| \\ &\leq \|x_n - x_{n+1}\| + \|\alpha_n(\rho Ux_n - \mu FTy_n) + Ty_n - Tx_n\| \\ &\leq \|x_n - x_{n+1}\| + \alpha_n \|\rho Ux_n - \mu FTy_n\| + \|y_n - x_n\| \\ &\leq \|x_n - x_{n+1}\| + \alpha_n \|\rho Ux_n - \mu FTy_n\| + \beta_n \|Sx_n - x_n\|. \end{aligned}$$

Notice that $\alpha_n \rightarrow 0$, $\beta_n \rightarrow 0$, $\|\rho Ux_n - \mu FTy_n\|$ and $\|Sx_n - x_n\|$ are bounded, and we have $\|x_n - Tx_n\| \rightarrow 0$ as $n \rightarrow \infty$.

Step 5. Now we show that $\limsup_{n \rightarrow \infty} \langle (\rho U - \mu F)x^*, x_n - x^* \rangle \leq 0$, where x^* is the unique solution of the variational inequality. Since $\{x_n\}$ is bounded, we take a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that

$$\limsup_{n \rightarrow \infty} \langle (\rho U - \mu F)x^*, x_n - x^* \rangle = \limsup_{k \rightarrow \infty} \langle (\rho U - \mu F)x^*, x_{n_k} - x^* \rangle,$$

and we assume $x_{n_k} \rightharpoonup x'$. By Lemma 2.4, we have $x' \in \text{Fix}(T)$. Therefore

$$\limsup_{n \rightarrow \infty} \langle (\rho U - \mu F)x^*, x_n - x^* \rangle = \langle (\rho U - \mu F)x^*, x' - x^* \rangle \leq 0.$$

Hence

$$\begin{aligned} \|x_{n+1} - x^*\|^2 &= \langle P_\Omega(V_n) - x^*, x_{n+1} - x^* \rangle \\ &= \langle P_\Omega(V_n) - V_n, P_\Omega(V_n) - x^* \rangle + \langle V_n - x^*, x_{n+1} - x^* \rangle \\ &\leq \langle \alpha_n(\rho Ux_n - \mu Fx^*) + (I - \alpha_n\mu F)Ty_n - (I - \alpha_n\mu F)Tx^*, x_{n+1} - x^* \rangle \\ &= \alpha_n \rho \langle Ux_n - Ux^*, x_{n+1} - x^* \rangle + \alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle \\ &\quad + \langle (I - \alpha_n\mu F)Ty_n - (I - \alpha_n\mu F)Tx^*, x_{n+1} - x^* \rangle \\ &\leq \alpha_n \rho \gamma \|x_n - x^*\| \cdot \|x_{n+1} - x^*\| + \alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle \\ &\quad + (1 - \alpha_n \nu) \|y_n - x^*\| \cdot \|x_{n+1} - x^*\|. \end{aligned} \quad (12)$$

On the other hand, taking $p = x^*$ in (8), we obtain $\|y_n - x^*\| \leq \|x_n - x^*\| + \beta_n \|Sx^* - x^*\|$. Together with (12), we have

$$\begin{aligned} \|x_{n+1} - x^*\|^2 &\leq \alpha_n \rho \gamma \|x_n - x^*\| \cdot \|x_{n+1} - x^*\| + \alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle \\ &\quad + (1 - \alpha_n \nu) (\|x_n - x^*\| + \beta_n \|Sx^* - x^*\|) \cdot \|x_{n+1} - x^*\| \\ &= [1 - \alpha_n(\nu - \rho \gamma)] \|x_n - x^*\| \cdot \|x_{n+1} - x^*\| + \alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle \\ &\quad + (1 - \alpha_n \nu) \beta_n \|Sx^* - x^*\| \cdot \|x_{n+1} - x^*\| \\ &\leq \frac{1 - \alpha_n(\nu - \rho \gamma)}{2} (\|x_n - x^*\|^2 + \|x_{n+1} - x^*\|^2) \\ &\quad + \alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle \\ &\quad + \beta_n \|Sx^* - x^*\| \cdot \|x_{n+1} - x^*\|, \end{aligned}$$

which implies that

$$\begin{aligned} \|x_{n+1} - x^*\|^2 &\leq \frac{1 - \alpha_n(\nu - \rho \gamma)}{1 + \alpha_n(\nu - \rho \gamma)} \|x_n - x^*\|^2 \\ &\quad + \frac{2}{1 + \alpha_n(\nu - \rho \gamma)} [\alpha_n \langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle + \beta_n M] \\ &\leq [1 - \alpha_n(\nu - \rho \gamma)] \|x_n - x^*\|^2 \end{aligned}$$

$$+ \alpha_n(v - \rho\gamma) \frac{2}{1 + \alpha_n(v - \rho\gamma)} \frac{1}{v - \rho\gamma} \\ \times \left(\langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle + \frac{\beta_n}{\alpha_n} M \right).$$

By the conditions (i) and (ii), we have $\sum_{n=0}^{\infty} \alpha_n(v - \rho\gamma) = \infty$ and

$$\limsup_{n \rightarrow \infty} \left(\langle \rho Ux^* - \mu Fx^*, x_{n+1} - x^* \rangle + \frac{\beta_n}{\alpha_n} M \right) \leq 0.$$

According to Lemma 2.6, we have $x_n \rightarrow x^*$.

Step 6. In particular, if we take $U = 0$, $F = I$, then $x_n \rightarrow x^*$, which implies that x^* is the minimum norm fixed point of T and x^* satisfies the variational inequality (5)

$$\langle (\rho U - \mu F)x^*, x - x^* \rangle \leq 0, \quad \forall x \in \text{Fix}(T).$$

So, $\forall x \in \text{Fix}(T)$, we deduce $\langle -\mu x^*, x - x^* \rangle \leq 0 \Rightarrow \langle x^*, x^* \rangle \leq \langle x, x^* \rangle \leq \|x\| \|x^*\|$, i.e., the point x^* is the unique solution to the quadratic minimization problem $x^* = \operatorname{argmin}_{x \in \text{Fix}(T)} \|x\|^2$. This completes the proof. \square

Remark 3.1 Prototypes for the iteration parameters in Theorem 3.1 are, for example, $\alpha_n = n^{-\xi}$, $\beta_n = n^{-\sigma}$ (with $\xi, \sigma : \frac{1}{2} < \xi < \sigma \leq 1$). It is not difficult to prove that the conditions (i)-(iii) are satisfied.

Remark 3.2 Our Theorem 3.1 improves and extends many recent corresponding main results of other authors (see, for example, [5, 13, 15–19]) in the following ways:

(a) Some self-mappings in other papers (see [15, 16, 19]) are extended to the cases of non-self-mappings. Such as the self-contraction mapping $f : H \rightarrow H$ in [15, 16, 19] is extended to the case of a Lipschitzian (possibly non-self-)mapping $U : C \rightarrow H$ on a nonempty closed convex subset C of H . The Lipschitzian and strongly monotone (self-)mapping $F : H \rightarrow H$ in [16] is extended to the case of a Lipschitzian and strongly monotone (possibly non-self-)mapping $F : C \rightarrow H$.

(b) The contractive mapping f with a coefficient $\alpha \in [0, 1)$ in other papers (see [15, 16, 18, 19]) is extended to the cases of the Lipschitzian mapping U with a coefficient constant $\gamma \in [0, \infty)$.

(c) The Mann-type iterative format in [15–17, 19] has been extended to the Ishikawa-type iterative format (7) in our Theorem 3.1. So, their iterative formats (2), (3), (4) and (6) are some special cases of our iterative format (7), and some of their main results have been included in our Theorem 3.1, respectively.

(d) The iterative approximating fixed point of T in Theorem 3.1 is also the unique solution of the variational inequality (5). In fact, (5) is a hierarchical fixed point problem which closely relates to a convex minimization problem. In hierarchical fixed point problem (1), if $S = I - (\rho U - \mu F)$, then we can get the variational inequality (5). In (5), if $U = 0$, then we get the variational inequality $\langle Fx^*, x - x^* \rangle \geq 0$, $\forall x \in \text{Fix}(T)$, which just is the variational inequality studied by Suzuki [19]. If the Lipschitzian mapping $U = f$, $F = I$, $\rho = \mu = 1$, we get the variational inequality $\langle (I - f)x^*, x - x^* \rangle \geq 0$, $\forall x \in \text{Fix}(T)$, which is the variational inequality studied by Yao *et al.* [18]. So, the results of Theorem 3.1 in this paper have many useful applications such as the quadratic minimization problem $x^* = \operatorname{argmin}_{x \in \text{Fix}(T)} \|x\|^2$.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally and significantly in this research work. All authors read and approved the final manuscript.

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